#### Push-Button Creation of an Optimized Application Specific OS

# Synthos



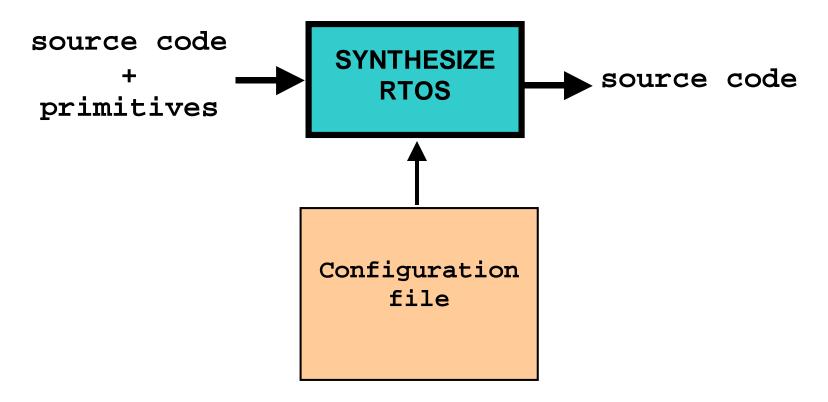
#### What is SynthOS?

- It is **NOT** an RTOS
- It is a tool that creates an RTOS (ASOS)
- One that requires no RTOS knowledge
- One that is optimized for your project
- One that is secure
- It is **NOT** an RTOS





# SynthOS







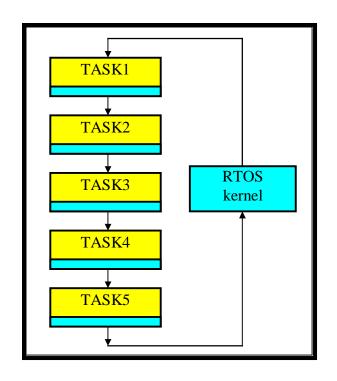
#### SynthOS Advantages

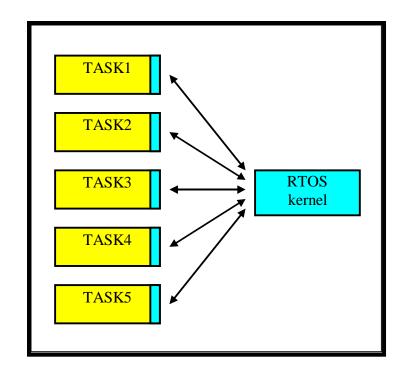
- Time to Market
- Security
- Cost of goods sold
- Development costs
- Power consumption
- <sub>i</sub> Portability
- Development and debugging
- Licensing





#### **Custom RTOS (ASOS)**



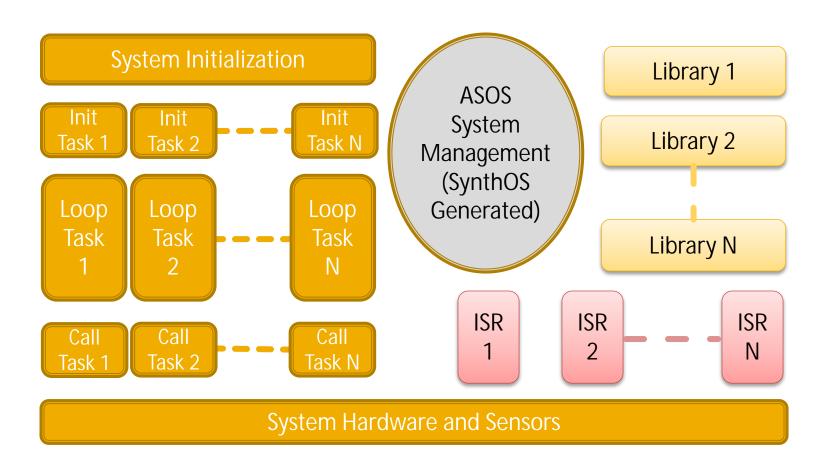


KEY: Task management code
User code





#### **System Architecture**







#### **Fast Time to Market**

- Small learning curve
- 19-page users guide
- 5 primitives
- Push a button, get an optimized OS





#### Low Cost of Goods Sold

- Supports low cost microcontrollers and microprocessors that off-the-shelf RTOSes don't support
- Requires smaller memory than an off-the-shelf RTOS
- Simpler system design





#### **Low Development Costs**

- Inexpensive software tool
- Reduced development time
- No RTOS purchase
- No RTOS royalty





# Case Study

Flat Panel Display Firmware Development					
CNA/ development and are the second	¢150,000				
SW developer salary + benefits	\$150,000		Lloina C	m+hOC	
	A atual Ca	ار باه	Using Sy		
Taal		Actual Schedule		Predicted Schedule	
Task	Man-weeks				
Writing firmware specification	6				
Code cyclic executive	6			\$2,884.62	
Code startup task	8	\$23,077	8		
Simple interface driver tasks	6	\$17,308	5.4	\$15,576.92	
Complex interface driver tasks	24	\$69,231	21.6	\$62,307.69	
Simple video controller tasks	8	\$23,077	7.2	\$20,769.23	
OSD controller tasks	8	\$23,077	7.2	\$20,769.23	
Advanced video controller tasks	12	\$34,615	10.8	\$31,153.85	
Internal tables for controlling video specs	2	\$5,769	2	\$5,769.23	
NVRAM control task	2	\$5,769	1.8	\$5,192.31	
Additional debug and integration	16.4	\$47,308	13.8	\$39,807.69	
Code optimization	6	\$17,308	4	\$11,538.46	
Documentation	4	\$11,538	3	\$8,653.85	
TOTAL	108.4	\$312,692	89.8	\$259,038	
Cost savings	\$53,654				
Time-to-Market savings (weeks)	9.3				





#### Strong security

- Every synthesized system is custom
- Hackers can't get a system to find vulnerabilities
- Vulnerabilities in one synthesized system are not found in other synthesized systems
- Can't add malware after synthesis





#### **Low Power Consumption**

- Supports low power microcontrollers and microprocessors that off-the-shelf RTOSes don't support
- Requires smaller memory than offthe-shelf RTOSes





#### Portability

- Works on any processor with a C compiler (i.e., any processor)
- Supports every new processor when it is available
- No need to develop new systems for new processors
- No need to find new RTOS to take advantage of new processors





# Development and Debugging

- Standard ANSI C output
- Use your current C development environment (IDE)
- Use your current C debugging tools
- Command line integrates with other tools





# Licensing

- No license restrictions on synthesized code
- All synthesized code is completely yours





#### Case Study: Multitasking Web Server

- Altera NIOS 32-bit soft processor
- Cyclone EP1C20 FPGA
- Took the Altera web server code
- Added functionality
- Turned single task into multitask system
- Kernel size: ~ 3K bytes





# Case Study: Heterogeneous Multiprocessing

- Xilinx Virtex-II Pro FPGA
- Xilinx MicroBlaze 32-bit soft processor
- PowerPC 32-bit hard processor
- MicroBlaze kernel size < 0.9 Kbytes
- PowerPC kernel size ~ 2.3 Kbytes
- Development time ~ 3 days





#### Case Study: Lego Mindstorm Robot

- Total RAM = 26K
- Lego RTOS = 22K
- BrickOS = 11K
- SynthOS = 2K





#### Arduino Robot Project

- Self directed robot
- Arduino Uno (Atmel ATmega328p)
  - § 32K flash
  - § 2K RAM
  - § 16 MHz clock
- Resources used

SynthOS	FreeRTOS
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8.6K flash 12.8K flash

0.5K RAM 1.25K RAM





#### **Arduino Robot Tasks**

- robot: Main *loop* task
- left\_motor: Left motor control *loop* task
- right\_motor: Right motor control *loop* task
- drive\_pan: Call task to manage scanning
  - and movements of the ultrasound sensor
- ultrasonic\_measure: Call task to control the
  - ultrasonic sensor distance calculation





## Arduino Robot Project







#### Costs

- Online
  - § Priority support, upgrades
- Single in-house license
  - § Priority support, upgrades
- In-house site license
  - § Priority support, upgrades

free

\$2,000 / year

\$20,000 / year

Negotiable



Synth OS

#### **Contact Info**

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